NEWS

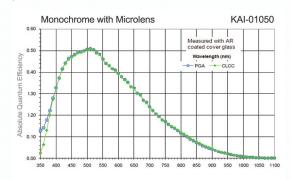
www.sacasa.info

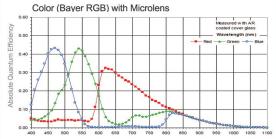
contact@sacasa.info

B1020



IMPERX: Technically superior products, full tech support, rapid-response customer care. "Bobcat 2.0" adds many new features, lens control, more memory and enhanced image quality. Each easy to use Bobcat is supported by IMPERX professionals.





INTERFACES AVAILABLE:

Resolution Sensor Sensor Format

Pixel Size

Frame Rate Standard Clock Frame Rate Overclocked Maximum Frame Rate Minimum S/N Ratio Output Format

Analog Gain Control
Black Level Control
Digital Gain and Offset
RGB Gain and Offset
White Balance
Shutter Speed
Exposure Control
Long Integration
Regions of Interest (ROI)
Binning H/V
Trigger Inputs

Trigger Options

Trigger Modes

Double Trigger (PIV) Interframe External Inputs/Outputs Strobe Output RS232 Interface Pulse Generator Image Overlay Image Enhancement

Internal DDR Memory On Board FIFO (GEV & PoE) Gamma Correction Data Corrections

Minimum Illumination Lens Mount Video Iris Control Iris, Zoom Focus Control Supply Input Range Power Consumption Size – Width/Height Size – Length

Weight
Vibration, Shock
Environmental
Humidity
MTBF
Regulatory

Camera Lin® Base (PoCL), GigE Vision, PoE, CoaXPress 1024 x 1024 (std.), 1032 x 1032 (max.)

KAI-01050, CCD

5.67mm (H) x 5.67mm (V) 7.96mm diagonal,

1/2" optical format

5.5 µm

40 MHz / 59 fps 50 MHz / 74 fps 338 fps

60dB

Mono CCD: 8, 10, 12, 14-bit (Single only)

Color CCD: 8, 10, 12

Manual, Auto: 0 - 36dB 1024 steps

Manual, 1024 steps

Manual Manual

Manual, auto, off

1us/step, 1/500,000 to 1/60 sec (nom)

Manual, auto, external Up to 16 seconds

7 ROIs, any line to any line, any pixel to any pixel 1x, 2x, 3x, 4x, 8x (Independent for H & V)

External (TTL via IN1/IN2), pulse generator,

software, computer

Level, edge, pulse width, internal exposure, up to 16 seconds trigger delay, debounce Free-run, standard, double, fast, asynchronous,

frame accumulation
Time: 200 nanoseconds

2 IN, 2 OUT, user programmable

2 strobes, programmable position and duration

Yes, programmable Yes, programmable

Optical center, programmable H & V lines

Threshold, contrast enhancement, knee correction, horizontal flip, negative image, bit shift (+/- 7 places)

nonzoniai ilip, negative image, bit shiit (+/- / piaces)

2Gb (256 MB) 1Gb (128 MB)

G=1.0, G=0.45, user upgradeable LUT

Defective/hot pixel correction (static, dynamic),

black level, vertical smear

1 Lux, F/ 1.4

C-Mount (Default), CS Auto, programmable Manual, user programmable

12VDC (10V - 15V), 1.5 A inrush

CLB 3.3 W, GEV 4.7w, PoE 5.9W, CXP TBD 46mm (W) x 46mm (H) – Applies to all interfaces CLB 58.3mm (L), GEV 76.2mm (L), PoE 89.8mm (L),

CXP 65.8mm (L)

CLB 165g, GEV 233g, PoE 343g, CXP 223g

100g (20-200) HZ XYZ, 1000g

-40°C to +85°C Operating, -50°C to +90°C Storage

10% to 90% non-condensing

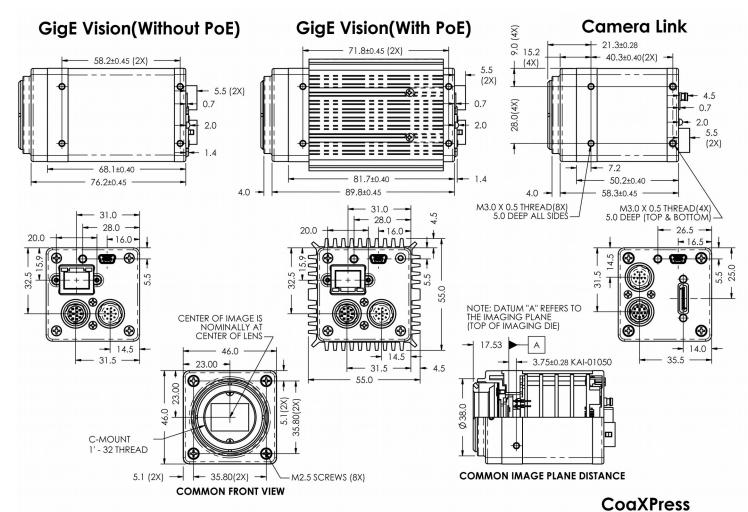
>660,000 hours @ 40°C (Telcordia SR-332)

FCC 15 part A, CE, RoHS









Hirose Connectors

Power and I/O Interface



- 12V DC Return * 7 **OUT1 Signal** +12V DC* IN1 Signal
- 3 IRIS VCC IN2 Signal IN1/2 Return 10 IRIS Video
- 4 IRIS Return 11 Reserved OUT1/2 Return 12 OUT2 Signal
- *Not connected for CXP

Connector: Hirose HR 10A- 10R- 12PB(71)

Lens Control/RS232

See manual for PIN information



- IRIS Return FOCUS + IRIS VCC ZOOM -
- 3 IRIS Video 700M+ 4 IRIS -10 UART_COM 5 IRIS+ 11 UART RX
- 6 FOCUS -12 UART_TX

Connector: Hirose HR 10A- 10R- 12SB(71)

B1020 Ordering Information

Interfaces available

Camera Link® Base (CLB) GigE Vision (GEV / PoE) CoaXPress (CXP)

Sensor types available

Monochrome **Bayer Color**

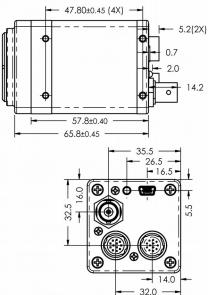
Accessories (Sold separately)

PS12v04-Power Supply w/ 1 input and 1 output

PS12v05-Power Supply (as above) and Video Iris



WWW.SACASA.INFO



Quality Management System ISO 9001:2008 Registered Environmental Management System ISO 14001:2004 Registered DDTC Registered (Directorate of Defense Trade Controls, US Department of State)

















1024 (H) x 1024 (V) Interline CCD Image Sensor

Description

The KAI-01050 Image Sensor is a 1-megapixel CCD in a 1/2" optical format. Based on the TRUESENSE 5.5 micron Interline Transfer CCD Platform, the sensor features broad dynamic range, excellent imaging performance, and a flexible readout architecture that enables use of 1, 2, or 4 outputs for full resolution readout up to 120 frames per second. A vertical overflow drain structure suppresses image blooming and enables electronic shuttering for precise exposure control. Other features include low dark current, negligible lag, and low smear.

The sensor shares common pin-out and electrical configurations with other devices based on the TRUESENSE 5.5 micron Interline Transfer CCD Platform, allowing a single camera design to support multiple members of this sensor family.

Table 1. GENERAL SPECIFICATIONS

| Parameter | Typical Value | | | | | |
|--|--|--|--|--|--|--|
| Architecture | Interline CCD, Progressive Scan | | | | | |
| Total Number of Pixels | 1084 (H) × 1064 (V) | | | | | |
| Number of Effective Pixels | 1040 (H) × 1040 (V) | | | | | |
| Number of Active Pixels | 1024 (H) × 1024 (V) | | | | | |
| Pixel Size | 5.5 μm (H) × 5.5 μm (V) | | | | | |
| Active Image Size | 5.632 mm (H) × 5.632 mm (V) 7.96 mm (diagonal), 1/2" Optical Format | | | | | |
| Aspect Ratio | 1:1 | | | | | |
| Number of Outputs | 1, 2, or 4 | | | | | |
| Charge Capacity | 20,000 electrons | | | | | |
| Output Sensitivity | 34 μV/e ⁻ | | | | | |
| Quantum Efficiency Monochrome (-ABA) R, G, B (-FBA) R, G, B (-CBA) | 44% 31%, 37%, 38% 29%, 37%, 39% | | | | | |
| Read Noise (f = 40 MHz) | 12 e ⁻ rms | | | | | |
| Dark Current Photodiode / VCCD | 7 / 140 e ⁻ /s | | | | | |
| Dark Current Doubling Temp Photodiode / VCCD | 7°C / 9°C | | | | | |
| Dynamic Range | 64 dB | | | | | |
| Charge Transfer Efficiency | 0.99999 | | | | | |
| Blooming Suppression | > 300 X | | | | | |
| Smear | -100 dB | | | | | |
| Image Lag | < 10 electrons | | | | | |
| Maximum Pixel Clock Speed | 40 MHz | | | | | |
| Maximum Frame Rate Quad / Dual / Single Output | 120 / 60 / 30 fps | | | | | |
| Package | 68 Pin PGA 64 Pin CLCC | | | | | |
| Cover Glass | AR Coated, 2-Sides | | | | | |

NOTE: All Parameters are specified at T = 40°C unless otherwise noted.



ON Semiconductor®

www.onsemi.com



Figure 1. KAI-01050 Interline CCD Image Sensor

Features

- Color or Monochrome Configurations
- Progressive Scan Readout
- Flexible Readout Architecture
- High Frame Rate
- High Sensitivity
- Low Noise Architecture
- Excellent Smear Performance
- Package Pin Reserved for Device Identification

Applications

- Industrial Imaging
- Medical Imaging
- Security

ORDERING INFORMATION

See detailed ordering and shipping information on page 2 of this data sheet.

ORDERING INFORMATION

Standard Devices

See full datasheet for ordering information associated with devices no longer recommended for new designs.

Table 2. ORDERING INFORMATION - STANDARD DEVICES

| Part Number | Description | Marking Code |
|---------------------|---|---------------|
| KAI-01050-ABA-JD-BA | Monochrome, Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Standard Grade | |
| KAI-01050-ABA-JD-AE | Monochrome, Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | KAI-01050-ABA |
| KAI-01050-ABA-FD-BA | Monochrome, Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Standard Grade | Serial Number |
| KAI-01050-ABA-FD-AE | Monochrome, Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | |
| KAI-01050-FBA-JD-BA | Gen2 Color (Bayer RGB), Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Standard Grade | |
| KAI-01050-FBA-JD-AE | Gen2 Color (Bayer RGB), Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | KAI-01050-FBA |
| KAI-01050-FBA-FD-BA | Gen2 Color (Bayer RGB), Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Standard Grade | Serial Number |
| KAI-01050-FBA-FD-AE | Gen2 Color (Bayer RGB), Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | |

See the ON Semiconductor *Device Nomenclature* document (TND310/D) for a full description of the naming convention used for image sensors. For reference documentation, including information on evaluation kits, please visit our web site at www.onsemi.com.

Not Recommended for New Designs

Table 3. ORDERING INFORMATION - NOT RECOMMENDED FOR NEW DESIGNS

| Part Number | Description | Marking Code |
|---------------------|---|---------------|
| KAI-01050-CBA-JD-BA | Gen1 Color (Bayer RGB), Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Standard Grade | |
| KAI-01050-CBA-JD-AE | Gen1 Color (Bayer RGB), Telecentric Microlens, PGA Package, Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | KAI-01050-CBA |
| KAI-01050-CBA-FD-BA | Gen1 Color (Bayer RGB), Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Standard Grade | Serial Number |
| KAI-01050-CBA-FD-AE | Gen1 Color (Bayer RGB), Telecentric Microlens, CLCC Package, Sealed Clear Cover Glass with AR Coating (Both Sides), Engineering Grade | |

DEVICE DESCRIPTION

Architecture

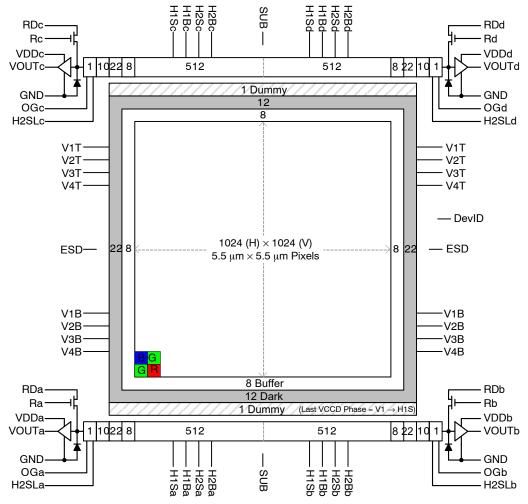


Figure 2. Block Diagram

Dark Reference Pixels

There are 12 dark reference rows at the top and 12 dark rows at the bottom of the image sensor. The dark rows are not entirely dark and so should not be used for a dark reference level. Use the 22 dark columns on the left or right side of the image sensor as a dark reference.

Under normal circumstances use only the center 20 columns of the 22 column dark reference due to potential light leakage.

Dummy Pixels

Within each horizontal shift register there are 11 leading additional shift phases. These pixels are designated as dummy pixels and should not be used to determine a dark reference level.

In addition, there is one dummy row of pixels at the top and bottom of the image.

Active Buffer Pixels

8 unshielded pixels adjacent to any leading or trailing dark reference regions are classified as active buffer pixels. These pixels are light sensitive but are not tested for defects and non-uniformities.

Image Acquisition

An electronic representation of an image is formed when incident photons falling on the sensor plane create electron-hole pairs within the individual silicon photodiodes. These photoelectrons are collected locally by the formation of potential wells at each photosite. Below photodiode saturation, the number of photoelectrons collected at each pixel is linearly dependent upon light level and exposure time and non-linearly dependent on wavelength. When the photodiodes charge capacity is reached, excess electrons are discharged into the substrate to prevent blooming.

ESD Protection

Adherence to the power-up and power-down sequence is critical. Failure to follow the proper power-up and power-down sequences may cause damage to the sensor. See Power-Up and Power-Down Sequence section.

Physical Description

PGA Pin Description and Device Orientation

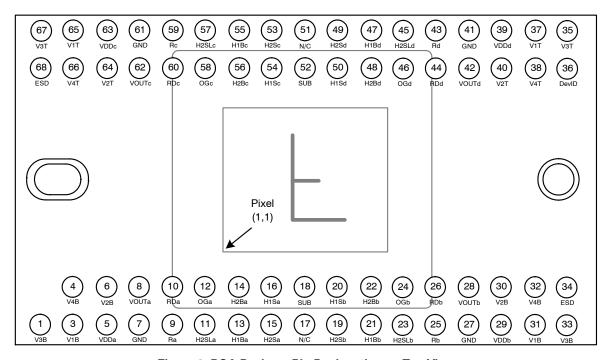


Figure 3. PGA Package Pin Designations - Top View

Table 4. PGA PACKAGE PIN DESCRIPTION

| Pin | Name | Description |
|-----|-------|--|
| 1 | V3B | Vertical CCD Clock, Phase 3, Bottom |
| 3 | V1B | Vertical CCD Clock, Phase 1, Bottom |
| 4 | V4B | Vertical CCD Clock, Phase 4, Bottom |
| 5 | VDDa | Output Amplifier Supply, Quadrant a |
| 6 | V2B | Vertical CCD Clock, Phase 2, Bottom |
| 7 | GND | Ground |
| 8 | VOUTa | Video Output, Quadrant a |
| 9 | Ra | Reset Gate, Quadrant a |
| 10 | RDa | Reset Drain, Quadrant a |
| 11 | H2SLa | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant a |
| 12 | OGa | Output Gate, Quadrant a |
| 13 | H1Ba | Horizontal CCD Clock, Phase 1, Barrier, Quadrant a |
| 14 | H2Ba | Horizontal CCD Clock, Phase 2, Barrier, Quadrant a |
| 15 | H2Sa | Horizontal CCD Clock, Phase 2, Storage, Quadrant a |
| 16 | H1Sa | Horizontal CCD Clock, Phase 1, Storage, Quadrant a |
| 17 | N/C | No Connect |
| 18 | SUB | Substrate |
| 19 | H2Sb | Horizontal CCD Clock, Phase 2, Storage, Quadrant b |
| 20 | H1Sb | Horizontal CCD Clock, Phase 1, Storage, Quadrant b |
| 21 | H1Bb | Horizontal CCD Clock, Phase 1, Barrier, Quadrant b |
| 22 | H2Bb | Horizontal CCD Clock, Phase 2, Barrier, Quadrant b |
| 23 | H2SLb | Horizontal CCD Clock, Phase 1, Storage, Last Phase, Quadrant b |

Table 4. PGA PACKAGE PIN DESCRIPTION (continued)

Liked named pins are internally connected and should have a common drive signal.
 N/C pins (17, 51) should be left floating.

Ceramic Leadless Chip Carrier Pin Description

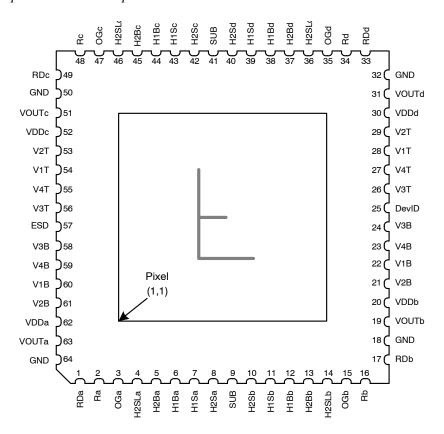


Figure 4. CLCC Package Pin Designations - Top View

Table 5. CLCC PACKAGE PIN DESCRIPTION

| Pin | Name | Description |
|-----|-------|--|
| 1 | RDa | Reset Drain, Quadrant a |
| 2 | Ra | Reset Gate, Quadrant a |
| 3 | OGa | Output Gate, Quadrant a |
| 4 | H2SLa | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant a |
| 5 | H2Ba | Horizontal CCD Clock, Phase 2, Barrier, Quadrant a |
| 6 | H1Ba | Horizontal CCD Clock, Phase 1, Barrier, Quadrant a |
| 7 | H1Sa | Horizontal CCD Clock, Phase 1, Storage, Quadrant a |
| 8 | H2Sa | Horizontal CCD Clock, Phase 2, Storage, Quadrant a |
| 9 | SUB | Substrate |
| 10 | H2Sb | Horizontal CCD Clock, Phase 2, Storage, Quadrant b |
| 11 | H1Sb | Horizontal CCD Clock, Phase 1, Storage, Quadrant b |
| 12 | H1Bb | Horizontal CCD Clock, Phase 1, Barrier, Quadrant b |
| 13 | H2Bb | Horizontal CCD Clock, Phase 2, Barrier, Quadrant b |
| 14 | H2SLb | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant b |
| 15 | OGb | Output Gate, Quadrant b |
| 16 | Rb | Reset Gate, Quadrant b |
| 17 | RDb | Reset Drain, Quadrant b |
| 18 | GND | Ground |
| 19 | VOUTb | Video Output, Quadrant b |
| 20 | VDDb | Output Amplifier Supply, Quadrant b |

Table 5. CLCC PACKAGE PIN DESCRIPTION (continued)

| | | · |
|----|-------|--|
| 21 | V2B | Vertical CCD Clock, Phase 2, Bottom |
| 22 | V1B | Vertical CCD Clock, Phase 1, Bottom |
| 23 | V4B | Vertical CCD Clock, Phase 4, Bottom |
| 24 | V3B | Vertical CCD Clock, Phase 3, Bottom |
| 25 | DevID | Device Identification |
| 26 | V3T | Vertical CCD Clock, Phase 3, Top |
| 27 | V4T | Vertical CCD Clock, Phase 4, Top |
| 28 | V1T | Vertical CCD Clock, Phase 1, Top |
| 29 | V2T | Vertical CCD Clock, Phase 2, Top |
| 30 | VDDd | Output Amplifier Supply, Quadrant d |
| 31 | VOUTd | Video Output, Quadrant d |
| 32 | GND | Ground |
| 33 | RDd | Reset Drain, Quadrant d |
| 34 | Rd | Reset Gate, Quadrant d |
| 35 | OGd | Output Gate, Quadrant d |
| 36 | H2SLd | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant d |
| 37 | H2Bd | Horizontal CCD Clock, Phase 2, Barrier, Quadrant d |
| 38 | H1Bd | Horizontal CCD Clock, Phase 1, Barrier, Quadrant d |
| 39 | H1Sd | Horizontal CCD Clock, Phase 1, Storage, Quadrant d |
| 40 | H2Sd | Horizontal CCD Clock, Phase 2, Storage, Quadrant d |
| 41 | SUB | Substrate |
| 42 | H2Sc | Horizontal CCD Clock, Phase 2, Storage, Quadrant c |
| 43 | H1Sc | Horizontal CCD Clock, Phase 1, Storage, Quadrant c |
| 44 | H1Bc | Horizontal CCD Clock, Phase 1, Barrier, Quadrant c |
| 45 | H2Bc | Horizontal CCD Clock, Phase 2, Barrier, Quadrant c |
| 46 | H2SLc | Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant c |
| 47 | OGc | Output Gate, Quadrant c |
| 48 | Rc | Reset Gate, Quadrant c |
| 49 | RDc | Reset Drain, Quadrant c |
| 50 | GND | Ground |
| 51 | VOUTc | Video Output, Quadrant c |
| 52 | VDDc | Output Amplifier Supply, Quadrant c |
| 53 | V2T | Vertical CCD Clock, Phase 2, Top |
| 54 | V1T | Vertical CCD Clock, Phase 1, Top |
| 55 | V4T | Vertical CCD Clock, Phase 4, Top |
| 56 | V3T | Vertical CCD Clock, Phase 3, Top |
| 57 | ESD | ESD Protection Disable |
| 58 | V3B | Vertical CCD Clock, Phase 3, Bottom |
| 59 | V4B | Vertical CCD Clock, Phase 4, Bottom |
| 60 | V1B | Vertical CCD Clock, Phase 1, Bottom |
| 61 | V2B | Vertical CCD Clock, Phase 2, Bottom |
| 62 | VDDa | Output Amplifier Supply, Quadrant a |
| | VOUTa | Video Output, Quadrant a |
| 63 | VOOTA | Vidoo Guipat, Quadrant a |

^{1.} Liked named pins are internally connected and should have a common drive signal.

IMAGING PERFORMANCE

Table 6. TYPICAL OPERATION CONDITIONS

Unless otherwise noted, the Imaging Performance Specifications are measured using the following conditions.

| Description | Condition | Notes |
|----------------------------|--|---|
| Frame Time | 71.6 msec | Electronic shutter is not used. Integration time equals frame time. |
| Horizontal Clock Frequency | 20 MHz | |
| Light Source | Continuous red, green and blue LED illumination centered at 450, 530 and 650 nm respectively | For monochrome sensor, only green LED used. |
| Operation | Nominal operating voltages and timing | |

Table 7. SPECIFICATIONS

| Description | Symbol | Min. | Nom. | Max. | Units | Sampling Plan | Temperature Tested At (°C) | Notes |
|---|-------------------|----------|----------|------|--------------------|------------------|----------------------------------|-------|
| Dark Field Global Non-Uniformity | DSNU | - | - | 2.0 | mVpp | Die | 27, 40 | |
| Bright Field Global Non-Uniformity | | - | 2.0 | 5.0 | %rms | Die | 27, 40 | 1 |
| Bright Field Global Peak to Peak Non-Uniformity | PRNU | - | 5.0 | 15.0 | %рр | Die | 27, 40 | 1 |
| Bright Field Center Non-Uniformity | | - | 1.0 | 2.0 | %rms | Die | 27, 40 | 1 |
| Maximum Photoresponse Nonlinearity | NL | _ | 2 | - | % | Design | | 2 |
| Maximum Gain Difference Between Outputs | ΔG | - | 10 | = | % | Design | | 2 |
| Maximum Signal Error due to Nonlinearity Differences | ΔNL | - | 1 | - | % | Design | | 2 |
| Horizontal CCD Charge Capacity | HNe | - | 55 | - | ke- | Design | | |
| Vertical CCD Charge Capacity | VNe | - | 45 | - | ke- | Design | | |
| Photodiode Charge Capacity | PNe | - | 20 | - | ke- | Die | 27, 40 | 3 |
| Horizontal CCD Charge Transfer Efficiency | HCTE | 0.999995 | 0.999999 | - | | Die | | |
| Vertical CCD Charge Transfer Efficiency | VCTE | 0.999995 | 0.999999 | - | | Die | | |
| Photodiode Dark Current | lpd | - | 7 | 70 | e/p/s | Die | 40 | |
| Vertical CCD Dark Current | lvd | - | 140 | 400 | e/p/s | Die | 40 | |
| Image Lag | Lag | - | - | 10 | e ⁻ | Design | | |
| Antiblooming Factor | Xab | 300 | - | - | | Design | | |
| Vertical Smear | Smr | - | -100 | - | dB | Design | | |
| Read Noise | n _{e-T} | _ | 12 | _ | e ⁻ rms | Design | | 4 |
| Dynamic Range | DR | - | 64 | - | dB | Design | | 4, 5 |
| Output Amplifier DC Offset | V _{odc} | - | 9.4 | - | V | Die | 27, 40 | |
| Output Amplifier Bandwidth | f _{-3db} | - | 250 | - | MHz | Die | | 6 |
| Output Amplifier Impedance | R _{OUT} | - | 127 | - | Ω | Die | 27, 40 | |
| Output Amplifier Sensitivity | ΔV/ΔΝ | - | 34 | - | μV/e- | Design | | |

^{1.} Per color

^{2.} Value is over the range of 10% to 90% of photodiode saturation.

^{3.} The operating value of the substrate voltage, VAB, will be marked on the shipping container for each device. The value of VAB is set such that the photodiode charge capacity is 680 mV.

^{4.} At 40 MHz

^{5.} Uses 20LOG (PNe/ n_{e-T})

^{6.} Assumes 5 pF load.

Table 8. KAI-01050-ABA CONFIGURATIONS

| Description | Symbol | Min. | Nom. | Max. | Units | Sampling Plan | Temperature Tested At (°C) | Notes |
|---------------------------------------|-------------------|------|------|------|-------|------------------|----------------------------------|-------|
| Peak Quantum Efficiency | QE _{max} | - | 44 | - | % | Design | | |
| Peak Quantum Efficiency Wavelength | λQE | - | 480 | _ | nm | Design | | |

Table 9. KAI-01050-FBA GEN2 COLOR CONFIGURATIONS WITH MAR GLASS

| Description | | Symbol | Min. | Nom. | Max. | Units | Sampling Plan | Temperature Tested At (°C) | Notes |
|---------------------------------------|----------------------|-------------------|------|-------------------|------|-------|------------------|----------------------------------|-------|
| Peak Quantum Efficiency | Blue Green Red | QE _{max} | - | 38 37 31 | - | % | Design | | |
| Peak Quantum Efficiency Wavelength | Blue Green Red | λQE | - | 460 530 605 | - | nm | Design | | |

Table 10. KAI-01050-CBA GEN1 COLOR CONFIGURATIONS WITH MAR GLASS

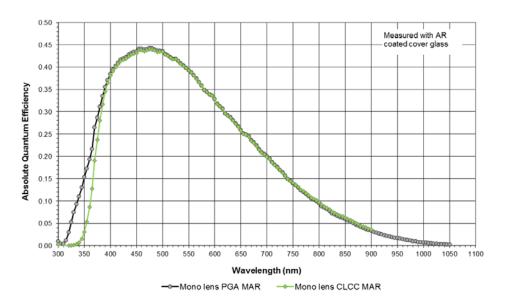
| Description | | Symbol | Min. | Nom. | Max. | Units | Sampling Plan | Temperature Tested At (°C) | Notes |
|---------------------------------------|----------------------|-------------------|------|-------------------|------|-------|------------------|----------------------------------|-------|
| Peak Quantum Efficiency | Blue Green Red | QE _{max} | - | 39 37 29 | - | % | Design | | 1 |
| Peak Quantum Efficiency Wavelength | Blue Green Red | λQE | - | 470 540 620 | - | nm | Design | | 1 |

^{1.} This color filter set configuration (Gen1) is not recommended for new designs.

TYPICAL PERFORMANCE CURVES

Quantum Efficiency

Monochrome with Microlens



NOTE: The PGA and CLCC versions have different quantum efficiencies due to differences in the cover glass transmission. See Figure 29: Cover Glass Transmission for more details.

Figure 5. Monochrome with Microlens Quantum Efficiency

Color (Bayer RGB) with Microlens (Gen2 and Gen1 CFA)

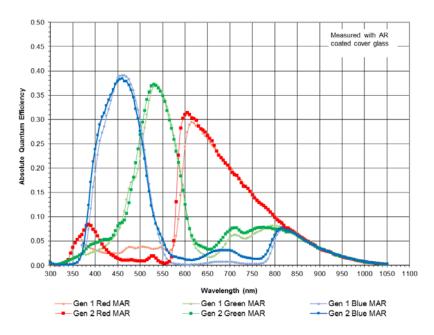


Figure 6. Gen2 and Gen1 Color (Bayer) with Microlens Quantum Efficiency

Angular Quantum Efficiency

For the curves marked "Horizontal", the incident light angle is varied in a plane parallel to the HCCD. For the curves marked "Vertical", the incident light angle is varied in a plane parallel to the VCCD.

Monochrome with Microlens

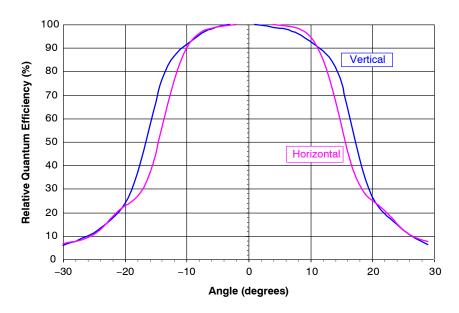


Figure 7. Monochrome with Microlens Angular Quantum Efficiency

Dark Current vs. Temperature

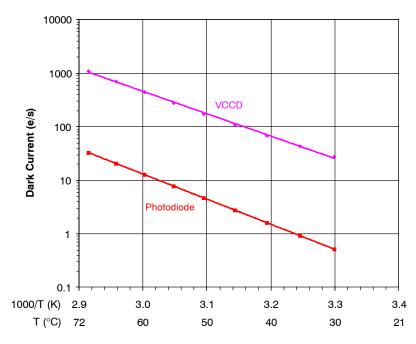


Figure 8. Dark Current vs. Temperature

Power-Estimated

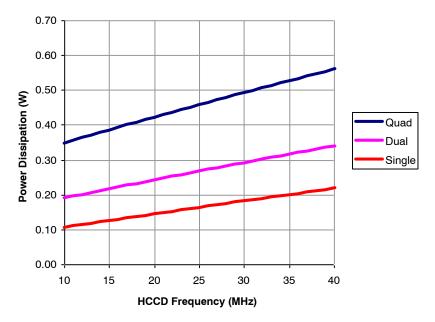


Figure 9. Power

Frame Rates

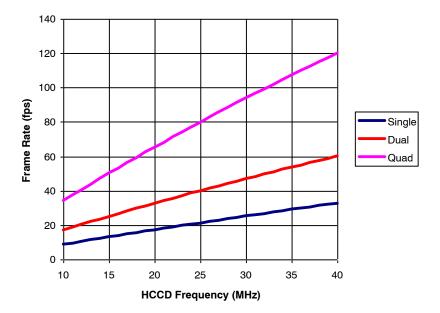


Figure 10. Frame Rates

DEFECT DEFINITIONS

Table 11. OPERATION CONDITIONS

| Description | Condition | Notes |
|----------------------------|--|--|
| Frame Time | 71.6 ms | Electronic shutter is not used. Integration time equals frame time. |
| Horizontal Clock Frequency | 20 MHz | |
| Light Source | Continuous Red, Green and Blue LED Illumination centered at 450, 530 and 650 nm respectively | For monochrome sensor, only green LED is used. |
| Operation | Nominal operating voltages and timing | |

Table 12. SPECIFICATIONS

| Description | Definition | Standard Grade | Notes |
|---|--|----------------|-------|
| Major Dark Field Defective Bright Pixel | Defect ≥ 25 mV | 10 | 2 |
| Major Bright Field Defective Dark Pixel | Defect ≥ 11% | 10 | 2 |
| Minor Dark Field Defective Bright Pixel | Defect ≥ 12 mV | 100 | 3 |
| Cluster Defect | A group of 2 contiguous major defective pixels. | 0 | 1, 2 |
| | A group of 3 to 10 contiguous major defective pixels. | 0 | |
| Column Defect | A group of more than 10 contiguous major defective pixels along a single column. | 0 | 1, 2 |

^{1.} Column and cluster defects are separated by no less than two (2) good pixels in any direction (excluding single pixel defects)

Defect Map

The defect map supplied with each sensor is based upon testing at an ambient (27° C) temperature. Minor point defects are not included in the defect map. All defective

pixels are reference to pixel 1, 1 in the defect maps. See Figure 11: Regions of Interest for the location of pixel 1, 1.

^{2.} Tested at 27°C and 40°C.

^{3.} Tested at 40°C.

TEST DEFINITIONS

Test Regions of Interest

Image Area ROI: Pixel (1, 1) to Pixel (1040, 1040)
Active Area ROI: Pixel (9, 9) to Pixel (1032, 1032)
Center ROI: Pixel (471, 471) to Pixel (570, 570)

Only the Active Area ROI pixels are used for performance and defect tests.

Overclocking

The test system timing is configured such that the sensor is overclocked in both the vertical and horizontal directions. See Figure 11 for a pictorial representation of the regions.

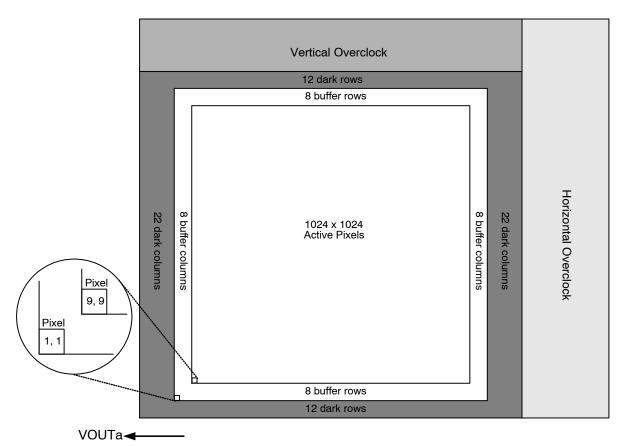


Figure 11. Regions of Interest

Tests

Dark Field Global Non-Uniformity

This test is performed under dark field conditions. The sensor is partitioned into 64 sub regions of interest, each of which is 128 by 128 pixels in size. See Figure 12: Test Sub Regions of Interest. The average signal level of each of the 64 sub regions of interest is calculated. The signal level of each of the sub regions of interest is calculated using the following formula:

Signal of ROI[i] = (ROI Average in Counts -

- Horizontal Overclock Average in Counts) ·
- · mV per Count

Units: mVpp (millivolts Peak to Peak)

Where i = 1 to 64. During this calculation on the 64 sub regions of interest, the maximum and minimum signal levels are found. The dark field global uniformity is then calculated

as the maximum signal found minus the minimum signal level found.

Global Non-Uniformity

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation (approximately 476 mV). Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. Global non-uniformity is defined as

Global Non–Uniformity =
$$100 \cdot \left(\frac{\text{Active Area Standard Deviation}}{\text{Active Area Signal}} \right)$$

Units: % rms

Active Area Signal = Active Area Average - Dark Column Average

Global Peak to Peak Non-Uniformity

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation

(approximately 476 mV). Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. The sensor is partitioned into 64 sub regions of interest, each of which is 128 by 128 pixels in size. See Figure 12: Test Sub Regions of Interest. The average signal level of each of the 64 sub regions of interest (ROI) is calculated. The signal level of each of the sub regions of interest is calculated using the following formula:

Where i = 1 to 64. During this calculation on the 64 sub regions of interest, the maximum and minimum signal levels are found. The global peak to peak uniformity is then calculated as:

Global Uniformity =
$$100 \cdot \left(\frac{\text{Max. Signal} - \text{Min. Signal}}{\text{Active Area Signal}} \right)$$

Units: % pp

Center Non-Uniformity

This test is performed with the imager illuminated to a level such that the output is at 70% of saturation (approximately 476 mV). Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. Defects are excluded for the calculation of this test. This test is performed on the center 100 by 100 pixels of the sensor. Center uniformity is defined as:

Center ROI Uniformity = 100 ·
$$\left(\frac{\text{Center ROI Standard Deviation}}{\text{Center ROI Signal}}\right)$$

Units: % rms

Center ROI Signal = Center ROI Average - Dark Colum Average

Dark Field Defect Test

This test is performed under dark field conditions. The sensor is partitioned into 64 sub regions of interest, each of which is 128 by 128 pixels in size. In each region of interest, the median value of all pixels is found. For each

region of interest, a pixel is marked defective if it is greater than or equal to the median value of that region of interest plus the defect threshold specified in the "Defect Definitions" section.

Bright Field Defect Test

This test is performed with the imager illuminated to a level such that the output is at approximately 476 mV. Prior to this test being performed the substrate voltage has been set such that the charge capacity of the sensor is 680 mV. The average signal level of all active pixels is found. The bright and dark thresholds are set as:

Dark Defect Threshold = Active Area Signal · Threshold

Bright Defect Threshold = Active Area Signal · Threshold

The sensor is then partitioned into 64 sub regions of interest, each of which is 128 by 128 pixels in size. In each region of interest, the average value of all pixels is found. For each region of interest, a pixel is marked defective if it is greater than or equal to the median value of that region of interest plus the bright threshold specified or if it is less than or equal to the median value of that region of interest minus the dark threshold specified.

Example for major bright field defective pixels:

- Average value of all active pixels is found to be 476 mV.
- Dark defect threshold: $476 \text{ mV} \cdot 11 \% = 52 \text{ mV}$.
- Bright defect threshold: $476 \text{ mV} \cdot 11 \% = 52 \text{ mV}$.
- Region of interest #1 selected. This region of interest is pixels 9, 9 to pixels 136, 136.
 - Median of this region of interest is found to be 470 mV.
 - Any pixel in this region of interest that is
 ≥ (470 + 52 mV) 522 mV in intensity will be marked
 defective.
 - Any pixel in this region of interest that is ≤ (470 – 52 mV) 418 mV in intensity will be marked defective.
- All remaining 64 sub regions of interest are analyzed for defective pixels in the same manner.

Pixel (1032,1032)

| 57 | 58 | 59 | 60 | 61 | 62 | 63 | 64 |
|----|----|----|----|----|----|----|----|
| 49 | 50 | 51 | 52 | 53 | 54 | 55 | 56 |
| 41 | 42 | 43 | 44 | 45 | 46 | 47 | 48 |
| 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 |
| 25 | 26 | 27 | 28 | 29 | 30 | 31 | 32 |
| 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 |
| 9 | 10 | 11 | 12 | 13 | 14 | 15 | 16 |
| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |

Pixel (9,9)

VOUTa ◀

Figure 12. Test Sub Regions of Interest

OPERATION

Absolute Maximum Ratings

Absolute maximum rating is defined as a level or condition that should not be exceeded at any time per the

description. If the level or the condition is exceeded, the device will be degraded and may be damaged. Operation at these values will reduce MTTF.

Table 13. ABSOLUTE MAXIMUM RATINGS

| Description | Symbol | Minimum | Maximum | Unit | Notes |
|-----------------------|------------------|---------|---------|------|-------|
| Operating Temperature | T _{OP} | -50 | 70 | °C | 1 |
| Humidity | RH | -5 | 90 | % | 2 |
| Output Bias Current | I _{OUT} | - | 60 | mA | 3 |
| Off-Chip Load | C _L | - | 10 | pF | |

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

- 1. Noise performance will degrade at higher temperatures.
- 2. T = 25°C. Excessive humidity will degrade MTTF.
- 3. Total for all outputs. Maximum current is -15 mA for each output. Avoid shorting output pins to ground or any low impedance source during operation. Amplifier bandwidth increases at higher current and lower load capacitance at the expense of reduced gain (sensitivity).

Table 14. ABSOLUTE MAXIMUM VOLTAGE RATINGS BETWEEN PINS AND GROUND

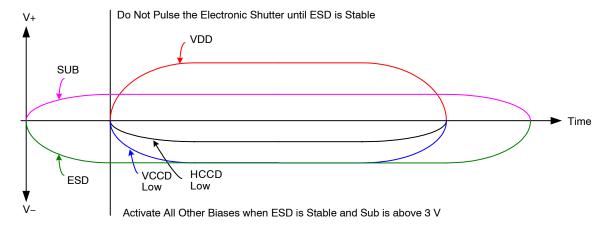
| Description | Minimum | Maximum | Unit | Notes |
|--|-----------|------------|------|-------|
| VDDα, VOUTα | -0.4 | 17.5 | V | 1 |
| RDα | -0.4 | 15.5 | V | 1 |
| V1B, V1T | ESD - 0.4 | ESD + 24.0 | V | |
| V2B, V2T, V3B, V3T, V4B, V4T | ESD - 0.4 | ESD + 14.0 | V | |
| H1Sα, H1Bα, H2Sα, H2Bα, H2SLα, Rα, OGα | ESD - 0.4 | ESD + 14.0 | V | 1 |
| ESD | -10.0 | 0.0 | V | |
| SUB | -0.4 | 40.0 | V | 2 |

^{1.} α denotes a, b, c or d.

^{2.} Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions

Power-Up and Power-Down Sequence

Adherence to the power-up and power-down sequence is critical. Failure to follow the proper power-up and power-down sequences may cause damage to the sensor.



Notes:

- 1. Activate all other biases when ESD is stable and SUB is above 3 V.
- 2. Do not pulse the electronic shutter until ESD is stable.
- 3. VDD cannot be $+15\ V$ when SUB is 0 V.
- 4. The image sensor can be protected from an accidental improper ESD voltage by current limiting the SUB current to less than 10 mA. SUB and VDD must always be greater than GND. ESD must always be less than GND. Placing diodes between SUB, VDD, ESD and ground will protect the sensor from accidental overshoots of SUB, VDD and ESD during power on and power off. See the figure below.

Figure 13. Power-Up and Power-Down Sequence

The VCCD clock waveform must not have a negative overshoot more than 0.4 V below the ESD voltage.

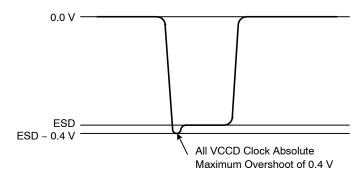


Figure 14. VCCD Clock Waveform

Example of external diode protection for SUB, VDD and ESD. α denotes a, b, c or d.

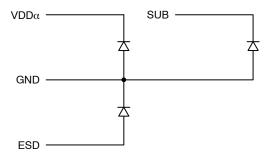


Figure 15. Example of External Diode Protection

DC Bias Operating Conditions

Table 15. DC BIAS OPERATING CONDITIONS

| Description | Pins | Symbol | Min. | Nom. | Max. | Unit | Max. DC Current | Notes |
|-------------------------|-------|------------------|------|----------|----------|------|--------------------|---------|
| Reset Drain | RDα | RD | 11.8 | 12.0 | 12.2 | V | 10 μΑ | 1 |
| Output Gate | OGα | OG | -2.2 | -2.0 | -1.8 | V | 10 μΑ | 1 |
| Output Amplifier Supply | VDDα | V_{DD} | 14.5 | 15.0 | 15.5 | V | 11.0 mA | 1, 2 |
| Ground | GND | GND | 0.0 | 0.0 | 0.0 | V | –1.0 mA | |
| Substrate | SUB | V _{SUB} | 5.0 | V_{AB} | V_{DD} | V | 50 μΑ | 3, 8 |
| ESD Protection Disable | ESD | ESD | -9.5 | -9.0 | Vx_L | V | 50 μΑ | 6, 7, 9 |
| Output Bias Current | VOUTα | I _{OUT} | -3.0 | -7.0 | -10.0 | mA | - | 1, 4, 5 |

- 1. α denotes a, b, c or d.
- The maximum DC current is for one output. I_{DD} = I_{OUT} + I_{SS}. See Figure 16.
 The operating value of the substrate voltage, V_{AB}, will be marked on the shipping container for each device. The value of V_{AB} is set such that the photodiode charge capacity is the nominal P_{Ne} (see Specifications).

 4. An output load sink must be applied to each VOUT pin to activate each output amplifier.
- 5. Nominal value required for 40 MHz operation per output. May be reduced for slower data rates and lower noise.
- Adherence to the power-up and power-down sequence is critical. See Power Up and Power Down Sequence section.
 ESD maximum value must be less than or equal to V1_L + 0.4 V and V2_L + 0.4 V.
- 8. Refer to Application Note *Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions*.
 9. Where Vx_L is the level set for V1_L, V2_L, V3_L, or V4_L in the application.

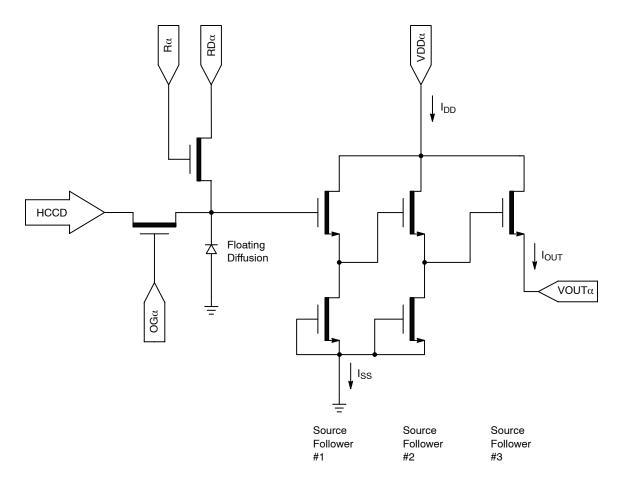


Figure 16. Output Amplifier

AC Operating Conditions

Table 16. CLOCK LEVELS

| Description | Pins (Note 1) | Symbol | Level | Min. | Nom. | Max. | Unit | Capacitance (Note 2) |
|--|------------------|-----------------|-----------|------------------|------|-----------------|------|-------------------------|
| Vertical CCD Clock, Phase 1 | V1B, V1T | V1_L | Low | -8.2 | -8.0 | -7.8 | V | 6 nF |
| | | V1_M | Mid | -0.2 | 0.0 | 0.2 | | (Note 6) |
| | | V1_H | High | 11.5 | 12.0 | 12.5 | | |
| Vertical CCD Clock, Phase 2 | V2B, V2T | V2_L | Low | -8.2 | -8.0 | -7.8 | V | 6 nF |
| | | V2_H | High | -0.2 | 0.0 | 0.2 | | (Note 6) |
| Vertical CCD Clock, Phase 3 | V3B, V3T | V3_L | Low | -8.2 | -8.0 | -7.8 | V | 6 nF |
| | | V3_H | High | -0.2 | 0.0 | 0.2 | | (Note 6) |
| Vertical CCD Clock, Phase 4 | V4B, V4T | V4_L | Low | -8.2 | -8.0 | -7.8 | V | 6 nF |
| | | V4_H | High | -0.2 | 0.0 | 0.2 | | (Note 6) |
| Horizontal CCD Clock, Phase 1 Storage | H1Sα | H1S_L | Low | -5.2 (Note 7) | -4.0 | -3.8 | V | 90 pF (Note 6) |
| | | H1S_A | Amplitude | 3.8 | 4.0 | 5.2 (Note 7) | | |
| Horizontal CCD Clock, Phase 1 Barrier | Η1Βα | H1B_L | Low | -5.2 (Note 7) | -4.0 | -3.8 | V | V 60 pF (Note 6) |
| | | H1B_A | Amplitude | 3.8 | 4.0 | 5.2 (Note 7) | | |
| Horizontal CCD Clock, Phase 2 Storage | H2Sα | H2S_L | Low | -5.2 (Note 7) | -4.0 | -3.8 | V | 90 pF (Note 6) |
| | | H2S_A | Amplitude | 3.8 | 4.0 | 5.2 (Note 7) | | |
| Horizontal CCD Clock, Phase 2 Barrier | Η2Βα | H2B_L | Low | -5.2 (Note 7) | -4.0 | -3.8 | V | 60 pF (Note 6) |
| | | H2B_A | Amplitude | 3.8 | 4.0 | 5.2 (Note 7) | | |
| Horizontal CCD Clock, | H2SLα | H2SL_L | Low | -5.2 | -5.0 | -4.8 | V | 20 pF |
| Phase 2 Last Phase (Note 3) | | H2SL_A | Amplitude | 4.8 | 5.0 | 5.2 | | (Note 6) |
| Reset Gate | Rα | R_L (Note 4) | Low | -3.5 | -2.0 | -1.5 | V | 16 pF (Note 6) |
| | | R_H | High | 2.5 | 3.0 | 4.0 | 1 | |
| Electronic Shutter (Note 5) | SUB | VES | High | 29.0 | 30.0 | 40.0 | V | 800 pF (Note 6) |
| | | | | | | | | |

^{1.} α denotes a, b, c or d.

^{2.} Capacitance is total for all like named pins.

Use separate clock driver for improved speed performance.
 Reset low should be set to -3 V for signal levels greater than 40,000 electrons.

^{5.} Refer to Application Note *Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions*.6. Capacitance values are estimated.

^{7.} If the minimum horizontal clock low level is used (–5.2 V), then the maximum horizontal clock amplitude should be used (5.2 V amplitude) to create a –5.2 V to 0.0 V clock. If a 5 V clock driver is used, the horizontal low level should be set to –5.0 V and the high level should be a set to 0.0 V.

The figure below shows the DC bias (VSUB) and AC clock (VES) applied to the SUB pin. Both the DC bias and AC clock are referenced to ground.

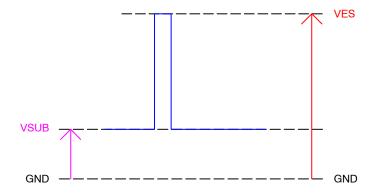


Figure 17. DC Bias and AC Clock Applied to the SUB Pin

Device Identification

The device identification pin (DevID) may be used to determine which Truesense Imaging 5.5 micron pixel interline CCD sensor is being used.

Table 17.

| Description | Pins | Symbol | Min. | Nom. | Max. | Unit | Max. DC Current | Notes |
|-----------------------|-------|--------|------|------|------|------|--------------------|-------|
| Device Identification | DevID | DevID | | ∞ | | Ω | n/a | 1, 2 |

- 1. For the KAI-01050, the DevID pin is not connected internally to the device. Thus the resistance on the pin is infinity.
- 2. If the Device Identification is not used, it may be left disconnected.

Recommended Circuit

Note that V1 must be a different value than V2.

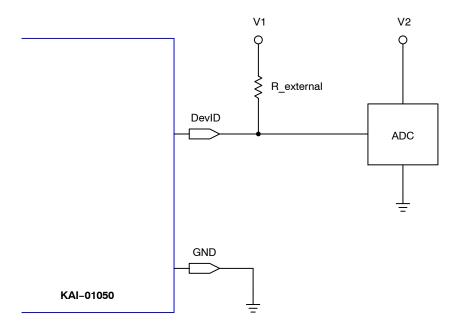


Figure 18. Device Identification Recommended Circuit

TIMING

Table 18. REQUIREMENTS AND CHARACTERISTICS

| Description | Symbol | Min. | Nom. | Max. | Unit | Notes |
|------------------------|-----------------------------------|-------|------|------|------|---------------------|
| Photodiode Transfer | t _{PD} | 1.0 | - | = | μs | |
| VCCD Leading Pedestal | t _{3P} | 4.0 | - | - | μs | |
| VCCD Trailing Pedestal | t _{3D} | 4.0 | - | - | μs | |
| VCCD Transfer Delay | t _D | 1.0 | - | - | μs | |
| VCCD Transfer | t _V | 1.0 | - | - | μs | |
| VCCD Clock Cross-Over | V _{VCR} | 75 | - | 100 | % | |
| VCCD Rise, Fall Times | t _{VR} , t _{VF} | 5 | _ | 10 | % | 2, 3 |
| HCCD Delay | t _{HS} | 0.2 | _ | _ | μs | |
| HCCD Transfer | t _e | 25.0 | _ | _ | ns | |
| Shutter Transfer | t _{SUB} | 1.0 | _ | _ | μs | |
| Shutter Delay | t _{HD} | 1.0 | - | - | μs | |
| Reset Pulse | t _R | 2.5 | - | - | ns | |
| Reset - Video Delay | t _{RV} | - | 2.2 | - | ns | |
| H2SL - Video Delay | t _{HV} | - | 3.1 | _ | ns | |
| Line Time | t _{LINE} | 15.53 | _ | _ | μs | Dual HCCD Readout |
| | | 29.35 | _ | - | 1 | Single HCCD Readout |
| Frame Time | t _{FRAME} | 8.26 | - | - | ms | Quad HCCD Readout |
| | | 16.52 | - | - | 1 | Dual HCCD Readout |
| | | 31.23 | _ | _ | | Single HCCD Readout |

Refer to timing diagrams as shown in Figure 19, Figure 20, Figure 21, Figure 22 and Figure 23.
 Refer to Figure 23: VCCD Clock Edge Alignment.
 Relative to the pulse width.

Timing Diagrams

The timing sequence for the clocked device pins may be represented as one of seven patterns (P1-P7) as shown in the table below. The patterns are defined in Figure 19 and

Figure 20. Contact ON Semiconductor Application Engineering for other readout modes.

Table 19. TIMING DIAGRAMS

| Device Pin | Quad Readout | Dual Readout VOUTa, VOUTb | Dual Readout VOUTa, VOUTc | Single Readout VOUTa |
|---------------------------|--------------|------------------------------|------------------------------|-----------------------------|
| V1T | P1T | P1B | P1T | P1B |
| V2T | P2T | P4B | P2T | P4B |
| V3T | P3T | P3B | P3T | P3B |
| V4T | P4T | P2B | P4T | P2B |
| V1B | | P | 1B | <u> </u> |
| V2B | | P2 | 2B | |
| V3B | | P | 3B | |
| V4B | | P | 4B | |
| H1Sa | | P | 25 | |
| H1Ba | | P | 25 | |
| H2Sa (Note 2) | | P | 26 | |
| H2Ba | | Р | 26 | |
| Ra | | Р | 77 | |
| H1Sb | | P5 | F | 25 |
| H1Bb | | P5 | F | 26 |
| H2Sb (Note 2) | | P6 | F | 26 |
| H2Bb | | P6 | F | 25 |
| Rb | | P7 | P7 (Note 1) or Off (Note 3) | P7 (Note 1) or Off (Note 3) |
| H1Sc | P5 | P5 (Note 1) or Off (Note 3) | P5 | P5 (Note 1) or Off (Note 3) |
| H1Bc | P5 | P5 (Note 1) or Off (Note 3) | P5 | P5 (Note 1) or Off (Note 3) |
| H2Sc (Note 2) | P6 | P6 (Note 1) or Off (Note 3) | P6 | P6 (Note 1) or Off (Note 3) |
| H2Bc | P6 | P6 (Note 1) or Off (Note 3) | P6 | P6 (Note 1) or Off (Note 3) |
| Rc | P7 | P7 (Note 1) or Off (Note 3) | P7 | P7 (Note 1) or Off (Note 3) |
| H1Sd | P5 | P5 (Note 1) or Off (Note 3) | P5 | P5 (Note 1) or Off (Note 3) |
| H1Bd | P5 | P5 (Note 1) or Off (Note 3) | P6 | P5 (Note 1) or Off (Note 3) |
| H2Sd (Note 2) | P6 | P6 (Note 1) or Off (Note 3) | P6 | P6 (Note 1) or Off (Note 3) |
| H2Bd | P6 | P6 (Note 1) or Off (Note 3) | P5 | P6 (Note 1) or Off (Note 3) |
| Rd | P7 | P7 (Note 1) or Off (Note 3) | P7 (Note 1) or Off (Note 3) | P7 (Note 1) or Off (Note 3) |
| | | | | |
| #Lines/Frame (Minimum) | 532 | 1064 | 532 | 1064 |

| #Lines/Frame (Minimum) | 532 | 1064 | 532 | 1064 |
|---------------------------|-----|------|-----|------|
| #Pixels/Line (Minimum) | 55 | 53 | 11 | 06 |

^{1.} For optimal performance of the sensor. May be clocked at a lower frequency. If clocked at a lower frequency, the frequency selected should be a multiple of the frequency used on the a and b register.

^{2.} H2SLx follows the same pattern as H2Sx For optimal speed performance, use a separate clock driver.

^{3.} Off = +5 V. Note that there may be operating conditions (high temperature and/or very bright light sources) that will cause blooming from the unused c/d register into the image area.

Photodiode Transfer Timing

A row of charge is transferred to the HCCD on the falling edge of V1 as indicated in the P1 pattern below. Using this timing sequence, the leading dummy row or line is combined with the first dark row in the HCCD. The "Last Line" is dependent on readout mode – either 532 or 1064 minimum counts required. It is important to note that, in

general, the rising edge of a vertical clock (patterns P1–P4) should be coincident or slightly leading a falling edge at the same time interval. This is particularly true at the point where P1 returns from the high (3^{rd} level) state to the mid-state when P4 transitions from the low state to the high state.

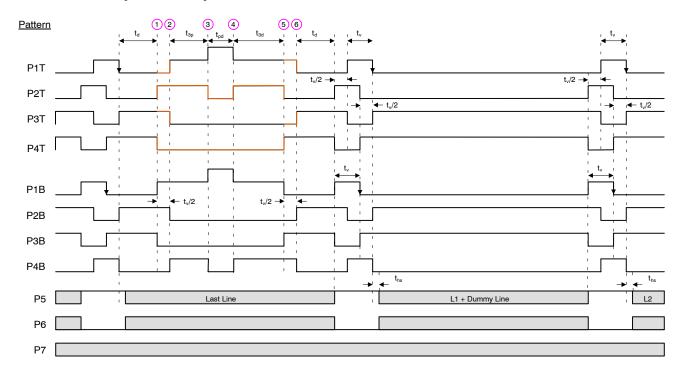


Figure 19. Photodiode Transfer Timing

Line and Pixel Timing

Each row of charge is transferred to the output, as illustrated below, on the falling edge of H2SL (indicated as

P6 pattern). The number of pixels in a row is dependent on readout mode – either 553 or 1106 minimum counts required.

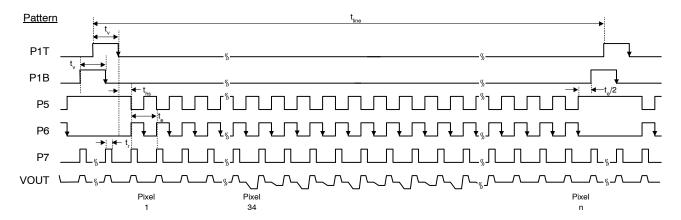


Figure 20. Line and Pixel Timing

Pixel Timing Detail

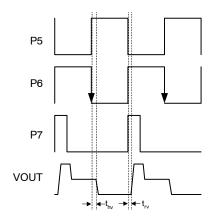


Figure 21. Pixel Timing Detail

Frame/Electronic Shutter Timing

The SUB pin may be optionally clocked to provide electronic shuttering capability as shown below. The

resulting photodiode integration time is defined from the falling edge of SUB to the falling edge of V1 (P1 pattern).

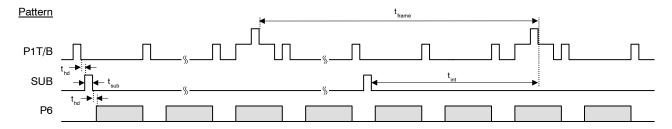


Figure 22. Frame/Electronic Shutter Timing

VCCD Clock Edge Alignment

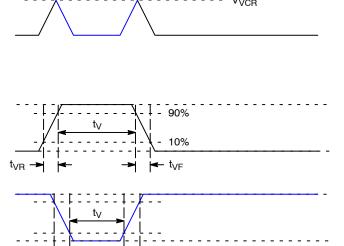


Figure 23. VCCD Clock Edge Alignment

Line and Pixel Timing – Vertical Binning by 2

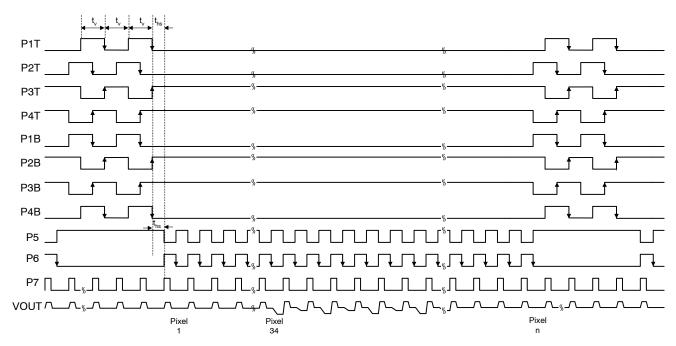


Figure 24. Line and Pixel Timing – Vertical Binning by 2

STORAGE AND HANDLING

Table 20. STORAGE CONDITIONS

| Description | Symbol | Minimum | Maximum | Units | Notes |
|---------------------|-----------------|---------|---------|-------|-------|
| Storage Temperature | T _{ST} | -55 | 80 | °C | 1 |
| Humidity | RH | 5 | 90 | % | 2 |

^{1.} Long-term storage toward the maximum temperature will accelerate color filter degradation.

For information on ESD and cover glass care and cleanliness, please download the *Image Sensor Handling and Best Practices* Application Note (AN52561/D) from www.onsemi.com.

For information on environmental exposure, please download the *Using Interline CCD Image Sensors in High Intensity Lighting Conditions* Application Note (AND9183/D) from www.onsemi.com.

For information on soldering recommendations, please download the Soldering and Mounting Techniques Reference Manual (SOLDERRM/D) from www.onsemi.com.

For quality and reliability information, please download the *Quality & Reliability* Handbook (HBD851/D) from www.onsemi.com.

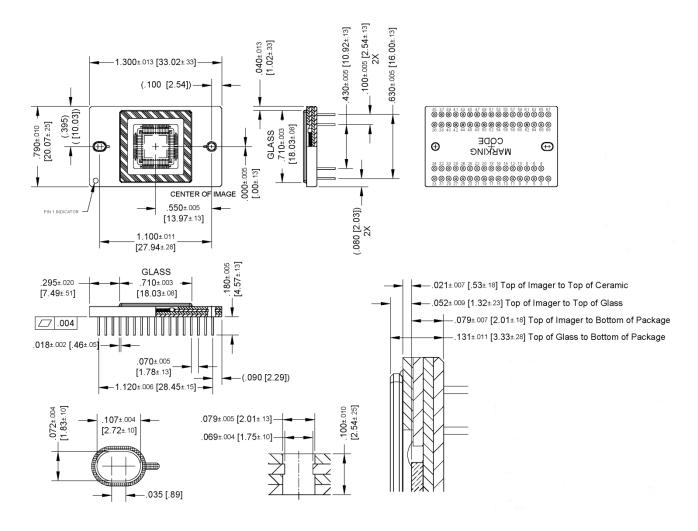
For information on device numbering and ordering codes, please download the *Device Nomenclature* technical note (TND310/D) from www.onsemi.com.

For information on Standard terms and Conditions of Sale, please download <u>Terms and Conditions</u> from <u>www.onsemi.com</u>.

^{2.} T = 25°C. Excessive humidity will degrade MTTF.

MECHANICAL INFORMATION

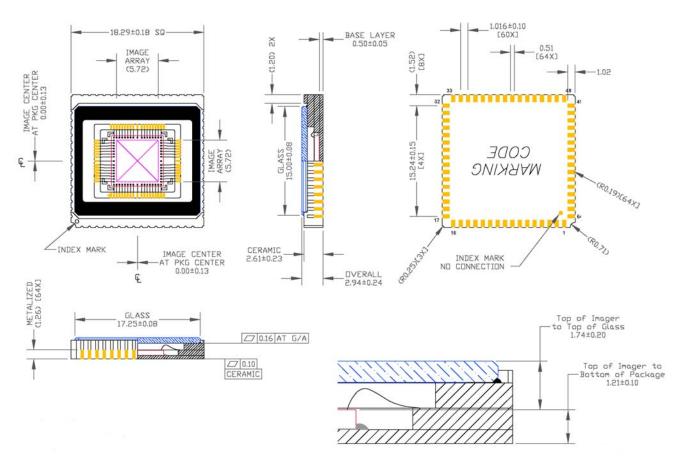
PGA Completed Assembly



- 1. See Ordering Information for marking code.
- 2. No materials to interfere with clearance through guide holes.
- 3. The center of the active image is nominally at the center of the package.
- 4. Die rotation < 0.5 degrees.
- 5. Glass rotation < 1.5 degrees
- 6. Internal traces may be exposed on sides of package. Do not allow metal to contact sides of ceramic package.
- 7. Recommended mounting screws:
 - a.) 1.6 × 0.35 mm (ISO Standard)
 - b.) 0-80 (Unified Fine Thread Standard).
- 8. Units: IN [MM]

Figure 25. PGA Completed Assembly

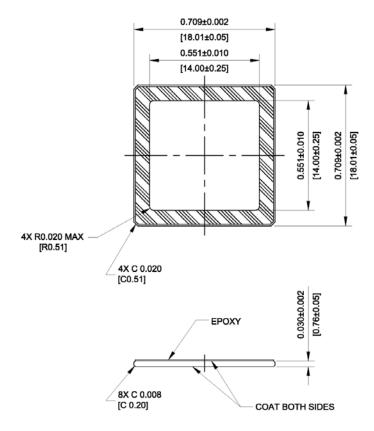
CLCC Completed Assembly



- 1. See Ordering Information for marking code.
- 2. Die rotation < 0.5 degrees.
- 3. Units: millimeters.

Figure 26. CLCC Completed Assembly

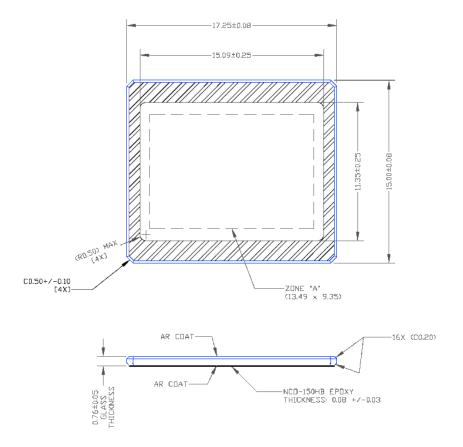
PGA Cover Glass



- Dust/Scratch Count 12 micron maximum
 Units: IN [MM]
 Reflectance Specification
 a. 420 nm to 435 nm < 2.0%
 b. 435 nm to 630 nm < 0.8%
- - c. 630 nm to 680 nm < 2.0%

Figure 27. PGA Cover Glass

CLCC MAR Cover Glass

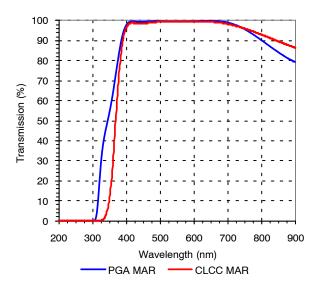


- 1. Dust/Scratch Count 12 micron maximum
- Units: millimeter
 Reflectance Specification

 - a. 420 nm to 435 nm < 2.0% b. 435 nm to 630 nm < 0.8%
 - c. 630 nm to 680 nm < 2.0%

Figure 28. CLCC MAR Cover Glass

Cover Glass Transmission



NOTE: PGA and CLCC MAR transmission data differ due to in-spec differences from glass vendor.

Figure 29. Cover Glass Transmission

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